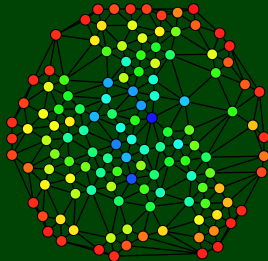
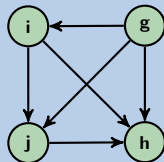
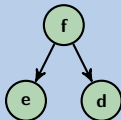
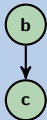


CS 2

Introduction to Programming Methods

Graphs 2: Representing Graphs Topological Sort





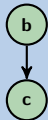
$$V = \{a\}, E = \emptyset$$

$$V = \{b, c\}, \\ E = \{(b, c)\}$$

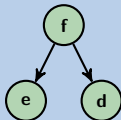
Let's extend our terminology for **directed graphs**!



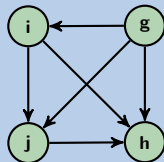
$$V = \{a\}, E = \emptyset$$



$$V = \{b, c\}, \\ E = \{(b, c)\}$$



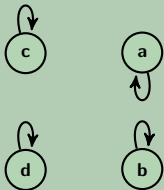
$$V = \{d, e, f\}, \\ E = \{(f, e), (f, d)\}$$



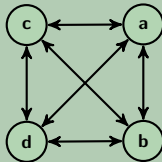
$$V = \{g, h, i, j\}, \\ E = \{(g, h), (h, i), (g, j), \\ (i, h), (j, h), (i, j)\}$$

Let's extend our terminology for **directed graphs**!

A Lonely Graph



Complete Directed Graph

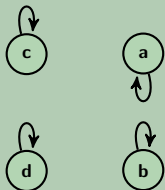


Some Questions

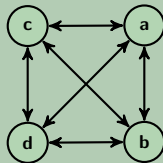
- How many edges can a **directed** graph with $|V| = n$ have?

- How many edges can a **directed** graph with $|V| = n$ and possible loops have?

A Lonely Graph



Complete Directed Graph



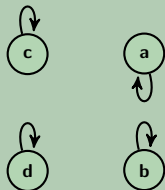
Some Questions

- How many edges can a **directed** graph with $|V| = n$ have?

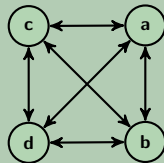
$$|E| = n(n - 1)$$

- How many edges can a **directed** graph with $|V| = n$ and possible loops have?

A Lonely Graph



Complete Directed Graph



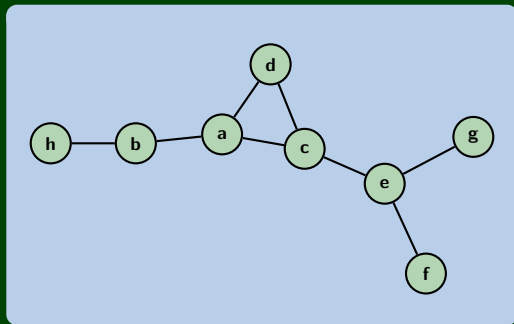
Some Questions

- How many edges can a **directed** graph with $|V| = n$ have?

$$|E| = n(n - 1)$$

- How many edges can a **directed** graph with $|V| = n$ and possible loops have?

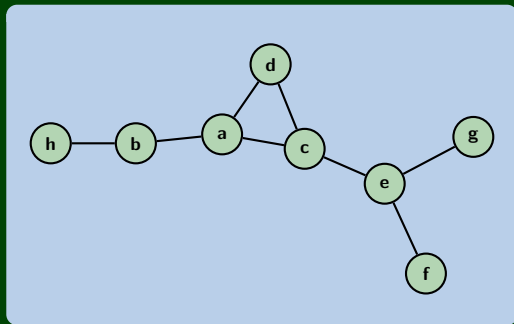
$$|E| = n^2$$



Definition (Degree)

The **degree** of a vertex in a graph is the number of vertices adjacent to it. In the above graph, we have:

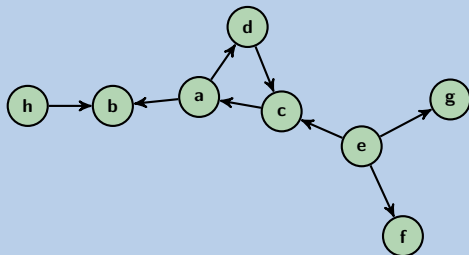
a	b	c	d	e	f	g	h



Definition (Degree)

The **degree** of a vertex in a graph is the number of vertices adjacent to it. In the above graph, we have:

a	b	c	d	e	f	g	h
3	2	3	2	3	1	1	1



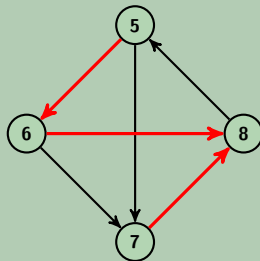
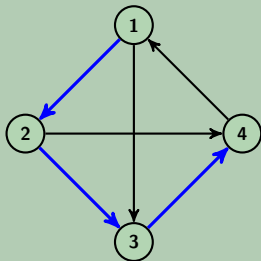
Definition (In & Out Degree)

The **in-degree** of a vertex, v , in a graph is $|\{(x,v) \mid (x,v) \in E, x \in V\}|$.

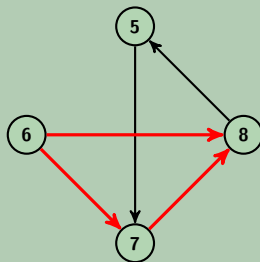
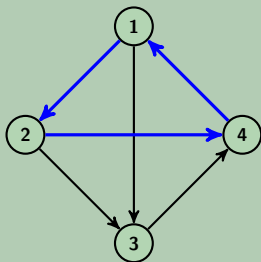
The **out-degree** of a vertex, v , in a graph is $|\{(v,x) \mid (v,x) \in E, x \in V\}|$.

	a	b	c	d	e	f	g	h
In-Degree	1	2	2	1	0	1	1	0
Out-Degree	2	0	1	1	3	0	0	1

Paths?

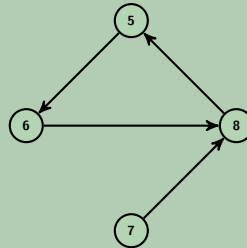
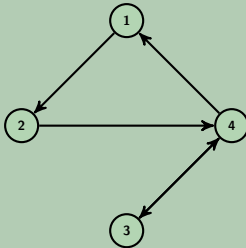


Cycle



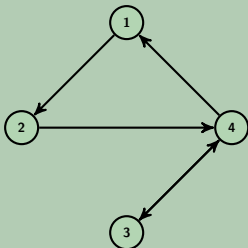
Definition (**Strongly** Connected Directed Graph)

We say a directed graph is **strongly connected** iff for every pair of vertices, $u, v \in V$, there is a path from u to v .

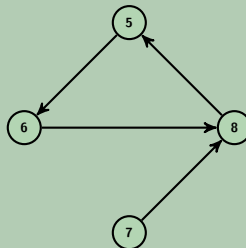


Definition (**Strongly** Connected Directed Graph)

We say a directed graph is **strongly connected** iff for every pair of vertices, $u, v \in V$, there is a path from u to v .



Strongly Connected!



Not Strongly Connected!

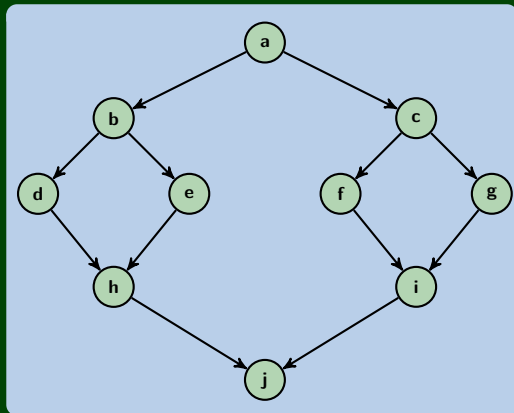
Definition (**Weakly** Connected Directed Graph)

We say a directed graph is **weakly connected** iff the underlying undirected graph is connected.

That is, if we “undirected the edges”, if the graph is connected, then the digraph is weakly connected.

Definition (DAG)

A **DAG** is a **directed, acyclic** graph.



By “acyclic”, we mean in the **directed** sense.

DAGs vs. Trees?

Is there a tree that isn't a DAG?

Is there a DAG that isn't a tree?

DAGs vs. Trees?

All trees are DAGs (remember, trees must be acyclic and connected!).

Not all DAGs are trees. See previous slide. Also, DAGs don't have to be connected!

Why DAGs?

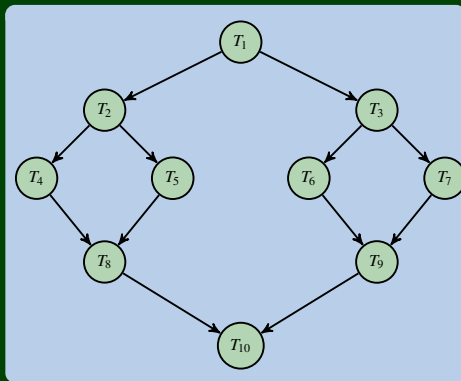
They come up a lot in practice. Cycles can be icky. Examples:

- Any sort of scheduling problem (scheduling your courses, scheduling fork-join threads, ...)
- Causal Structures (Bayesian Networks)
- Genealogy
- ...

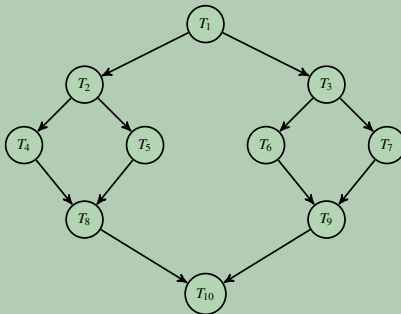
Topological Sort

Given a DAG ($G = (V, E)$), output all the vertices in an order such that no vertex appears before any vertex that has an edge to it.

“Output an order to process the graph that meets all dependencies”



How Many Valid Topological Sorts?



- $T_1, T_2, T_3, T_4, T_5, T_6, T_7, T_8, T_9, T_{10}$
- $T_1, T_2, T_4, T_3, T_5, T_6, T_7, T_8, T_9, T_{10}$
- $T_1, T_2, T_5, T_4, T_3, T_6, T_7, T_8, T_9, T_{10}$
- $T_1, T_3, T_6, T_7, T_9, T_2, T_5, T_4, T_8, T_{10}$
- ...

Implementing Topological Sort

Throw all the **in-degrees** in a priority queue. `removeMin()` repeatedly.

- This works, but it's **too slow**.
- Insight: PriorityQueues must deal with negative numbers; indegree will never be negative!
- Instead: Split ready vs. not ready (0 vs. non-zero) sets
- The “ready set” is a worklist!

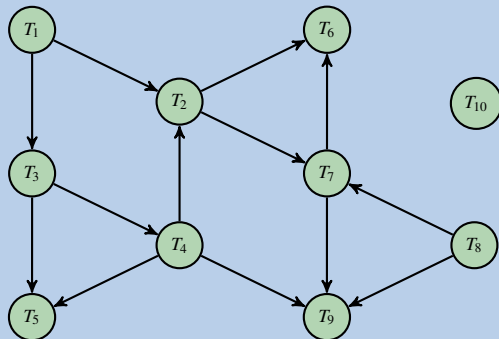
Setup

```
1 output = []
2 deps = {}
3 worklist = []
4 for (v : vertices) {
5     deps[v] = in-degree(v);
6     if (deps[v] == 0) {
7         worklist.add(v);
8     }
9 }
```

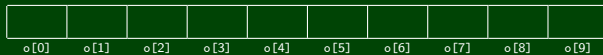
Do Work

```
1 while (worklist.hasWork()) {
2     v = worklist.next();
3     output.add(v);
4     for (w : neighbors(v)) {
5         deps[w] -= 1
6         if (deps[w] == 0) {
7             worklist.add(w);
8         }
9     }
10 }
```

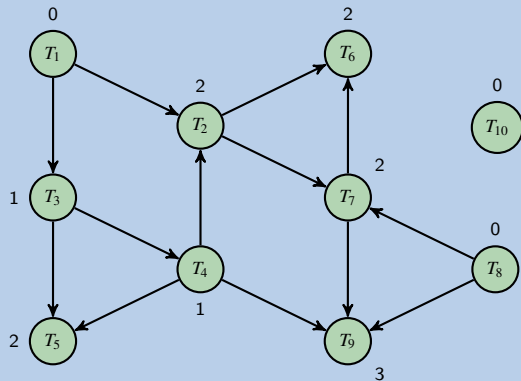
worklist ←



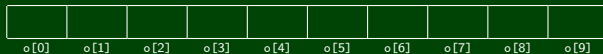
output



worklist ←



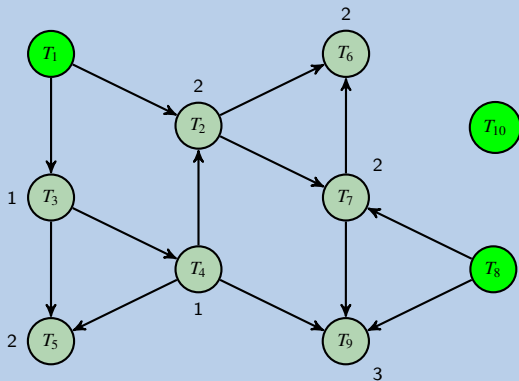
output



worklist ←

T_1	T_8	T_{10}
-------	-------	----------

 ←



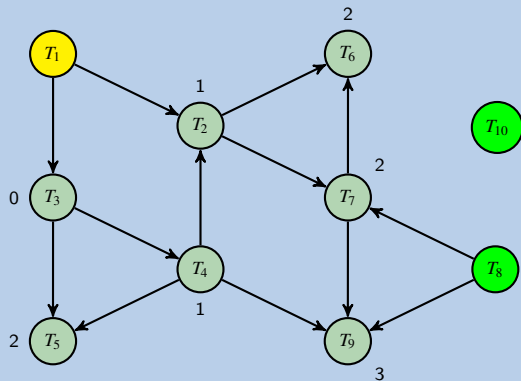
output

o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

worklist ←

T_8	T_{10}
-------	----------

 ←



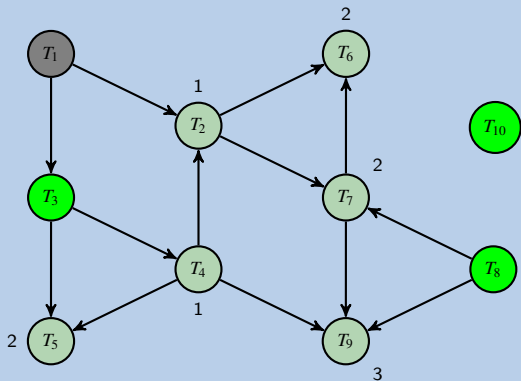
output

T_1									
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

worklist ←

T_8	T_{10}	T_3
-------	----------	-------

 ←



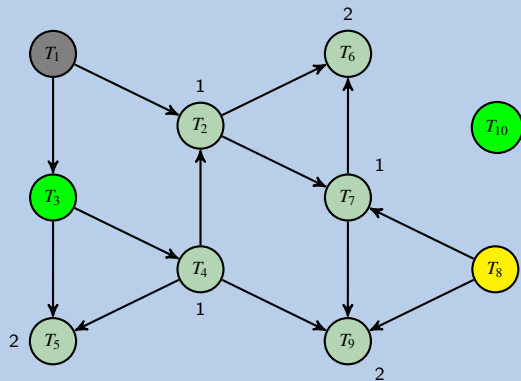
output

T_1									
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

worklist ←

T_{10}	T_3
----------	-------

 ←



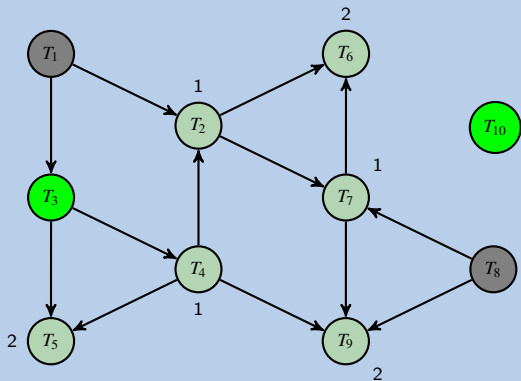
output

T_1	T_8								
$o[0]$	$o[1]$	$o[2]$	$o[3]$	$o[4]$	$o[5]$	$o[6]$	$o[7]$	$o[8]$	$o[9]$

worklist ←

T_{10}	T_3
----------	-------

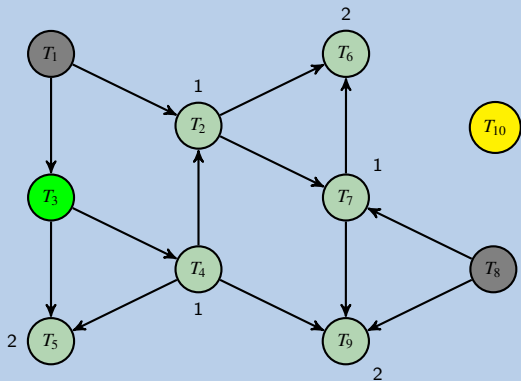
 ←



output

T_1	T_8								
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

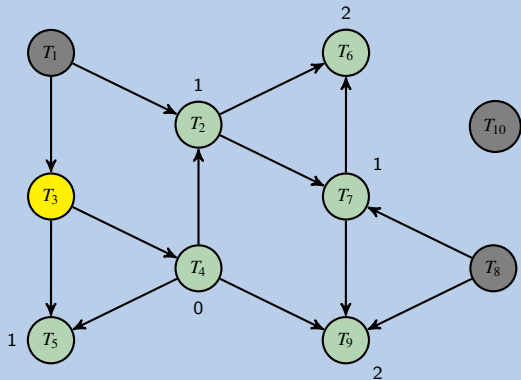
worklist ← T_3 ←



output

T_1	T_8	T_{10}							
$o[0]$	$o[1]$	$o[2]$	$o[3]$	$o[4]$	$o[5]$	$o[6]$	$o[7]$	$o[8]$	$o[9]$

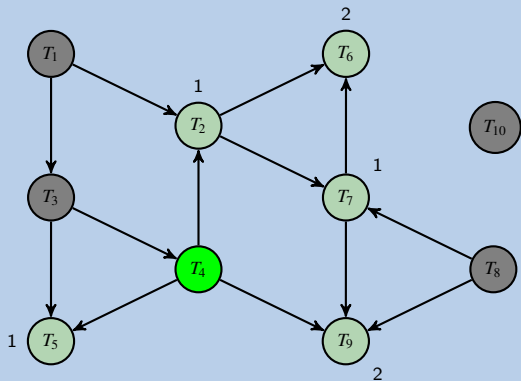
worklist ←



output

T_1	T_8	T_{10}	T_3						
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

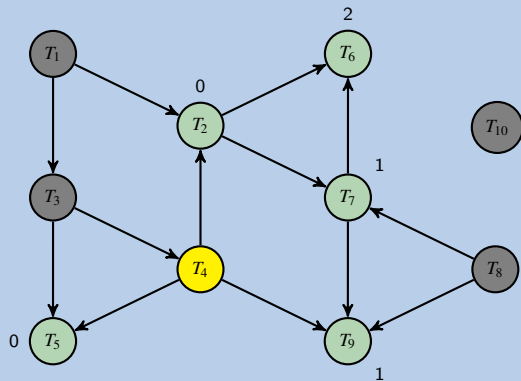
worklist ← T_4 ←



output

T_1	T_8	T_{10}	T_3						
<small>o[0]</small>	<small>o[1]</small>	<small>o[2]</small>	<small>o[3]</small>	<small>o[4]</small>	<small>o[5]</small>	<small>o[6]</small>	<small>o[7]</small>	<small>o[8]</small>	<small>o[9]</small>

worklist ←



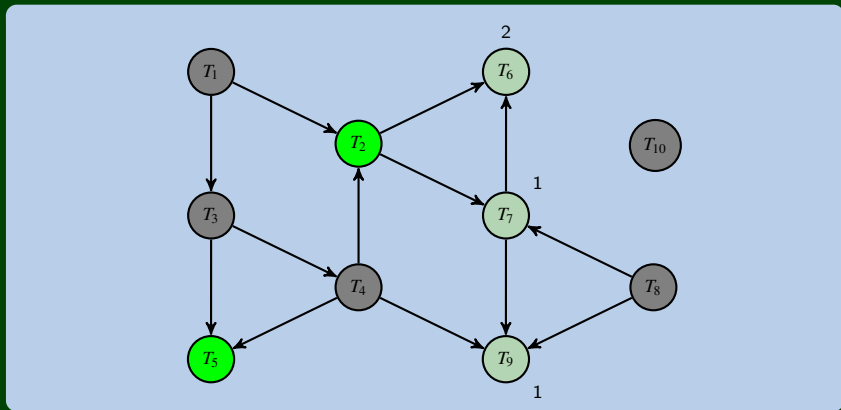
output

T_1	T_8	T_{10}	T_3	T_4					
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

worklist ←

T_2	T_5
-------	-------

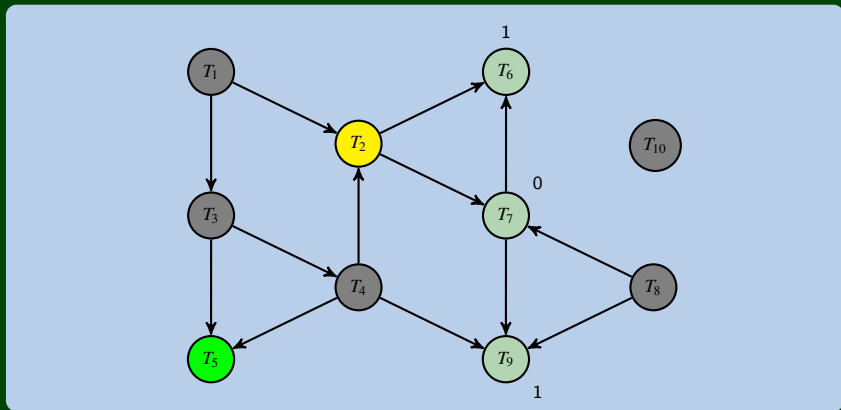
 ←



output

T_1	T_8	T_{10}	T_3	T_4					
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

worklist ← T_5 ←



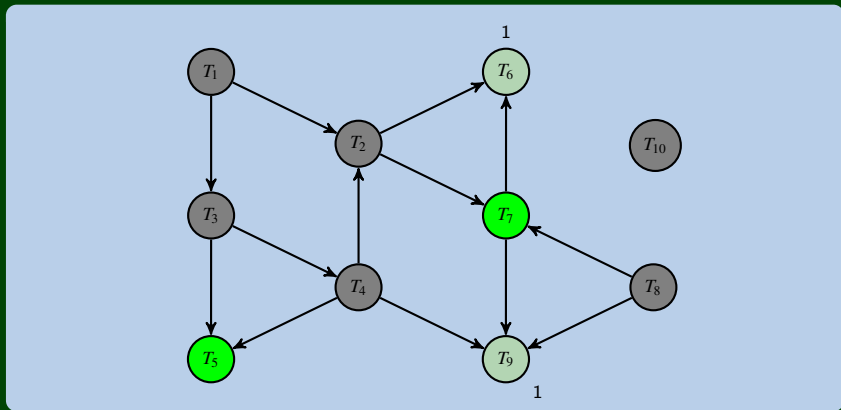
output

T_1	T_8	T_{10}	T_3	T_4	T_2				
$\circ[0]$	$\circ[1]$	$\circ[2]$	$\circ[3]$	$\circ[4]$	$\circ[5]$	$\circ[6]$	$\circ[7]$	$\circ[8]$	$\circ[9]$

worklist ←

T_5	T_7
-------	-------

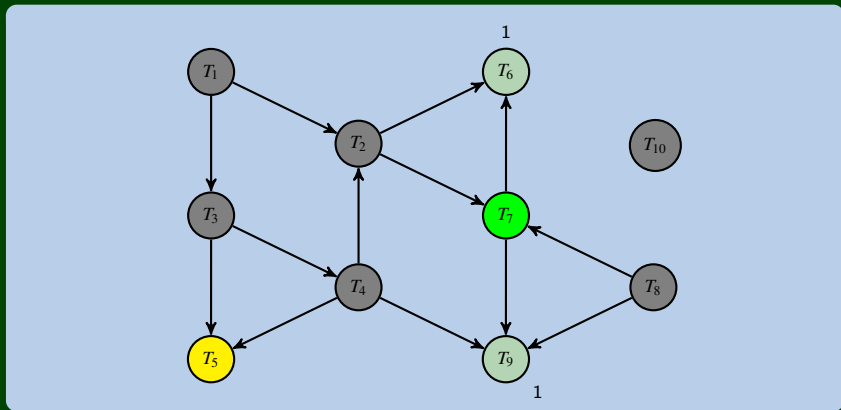
 ←



output

T_1	T_8	T_{10}	T_3	T_4	T_2				
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

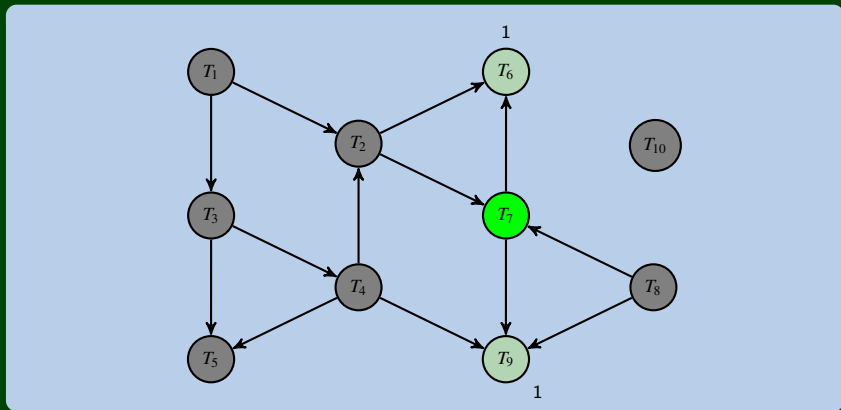
worklist ← T_7 ←



output

T_1	T_8	T_{10}	T_3	T_4	T_2	T_5			
<small>o[0]</small>	<small>o[1]</small>	<small>o[2]</small>	<small>o[3]</small>	<small>o[4]</small>	<small>o[5]</small>	<small>o[6]</small>	<small>o[7]</small>	<small>o[8]</small>	<small>o[9]</small>

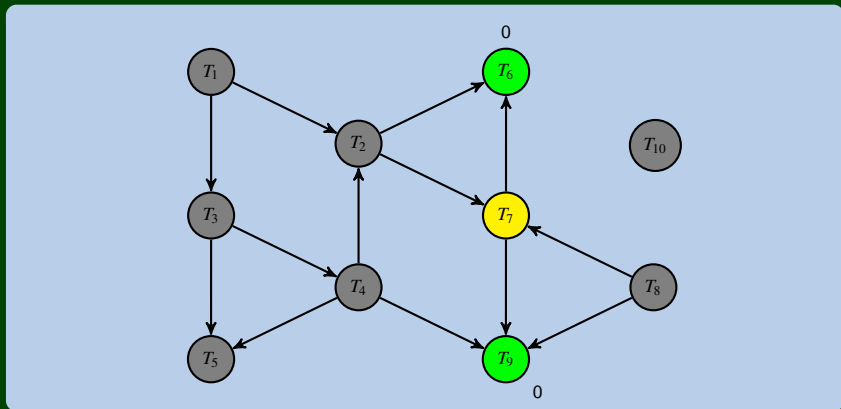
worklist ← T_7 ←



output

T_1	T_8	T_{10}	T_3	T_4	T_2	T_5			
$\circ[0]$	$\circ[1]$	$\circ[2]$	$\circ[3]$	$\circ[4]$	$\circ[5]$	$\circ[6]$	$\circ[7]$	$\circ[8]$	$\circ[9]$

worklist ←



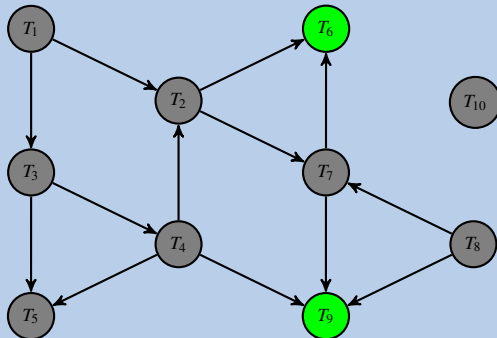
output

T_1	T_8	T_{10}	T_3	T_4	T_2	T_5	T_7		
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

worklist ←

T_6	T_9
-------	-------

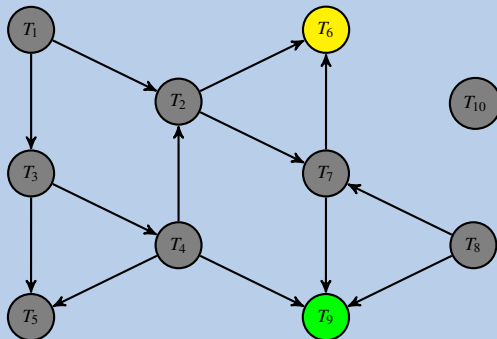
 ←



output

T_1	T_8	T_{10}	T_3	T_4	T_2	T_5	T_7		
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]

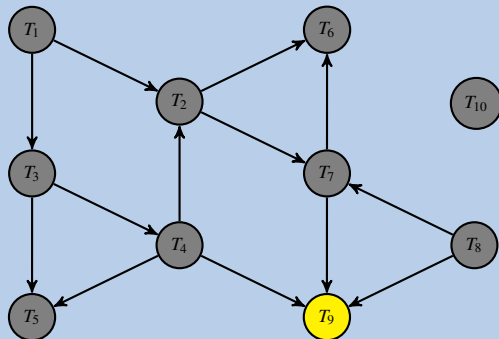
worklist ← T_9 ←



output

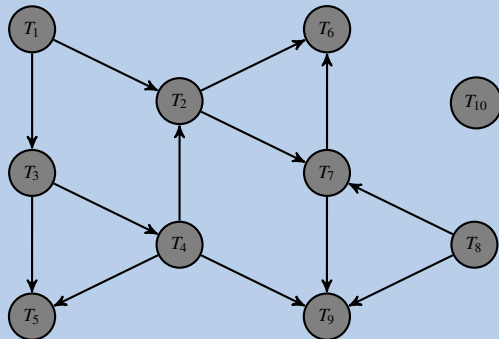
T_1	T_8	T_{10}	T_3	T_4	T_2	T_5	T_7	T_6	
$\circ[0]$	$\circ[1]$	$\circ[2]$	$\circ[3]$	$\circ[4]$	$\circ[5]$	$\circ[6]$	$\circ[7]$	$\circ[8]$	$\circ[9]$

worklist ←



output

T_1	T_8	T_{10}	T_3	T_4	T_2	T_5	T_7	T_6	T_9
o[0]	o[1]	o[2]	o[3]	o[4]	o[5]	o[6]	o[7]	o[8]	o[9]



What happens if there is a cycle?

Our worklist will be empty before we've processed all of the vertices. (e.g., "there are no nodes ready to print next, but we haven't gone through all of them")

In this case: our algorithm should throw a "not a DAG exception".

Runtime?

- Setup: We follow every edge for every vertex: $\mathcal{O}(|V| + |E|)$
- We add/remove each vertex from the work list once: $\mathcal{O}(|V|)$
- We decrement each indegree until zero (once for each edge): $\mathcal{O}(|E|)$
- So, overall, it's graph linear!