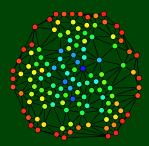
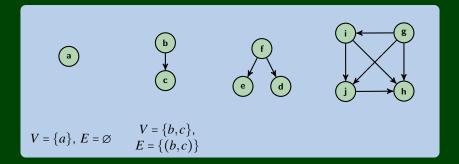
CS 2: Introduction to Programming Methods

Graphs 2: Representing Graphs Topological Sort

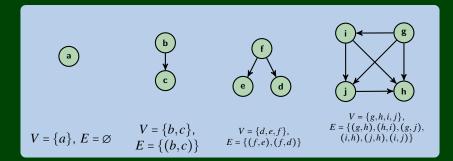


A Directed Graph is a Thingy...



Let's extend our terminology for directed graphs!

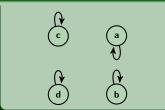
A Directed Graph is a Thingy...



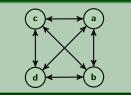
Let's extend our terminology for directed graphs!

More Graphs

A Lonely Graph



Complete Directed Graph



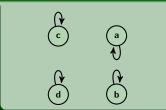
Some Questions

• How many edges can a **directed** graph with |V| = n have?

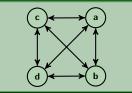
How many edges can a directed graph with |V| = n and possible loops have?

More Graphs

A Lonely Graph



Complete Directed Graph



Some Questions

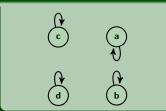
• How many edges can a **directed** graph with |V| = n have?

$$|E| = n(n-1)$$

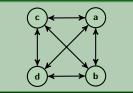
How many edges can a directed graph with |V| = n and possible loops have?

More Graphs

A Lonely Graph



Complete Directed Graph



Some Questions

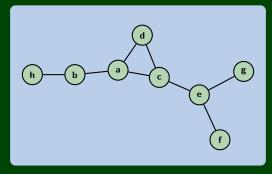
• How many edges can a **directed** graph with |V| = n have?

$$|E| = n(n-1)$$

How many edges can a directed graph with |V| = n and possible loops have?

$$|E| = n^2$$

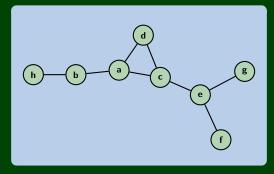
New Terminology: Degree



Definition (Degree)

The **degree** of a vertex in a graph is the number of vertices adjacent to it. In the above graph, we have:

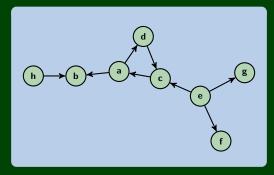
New Terminology: Degree



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Burgers? Now?

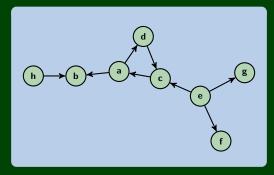


Definition (In & Out Degree)

The **in-degree** of a vertex, v, in a graph is $|\{(x,v) | (x,v) \in E, x \in V\}|$. The **out-degree** of a vertex, v, in a graph is $|\{(v,x) | (x,v) \in E, x \in V\}|$.

	а	b	с	d	е	f	g	h
In-Degree								
Out-Degree								

Burgers? Now?

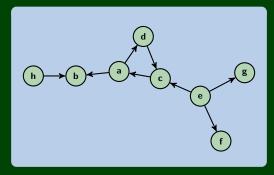


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	а	b	с	d	е	f	g	h
In-Degree	1	2	2	1	0	1	1	0
Out-Degree								

Burgers? Now?



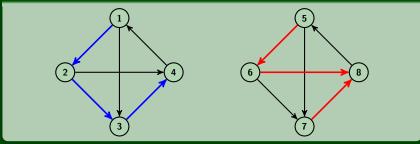
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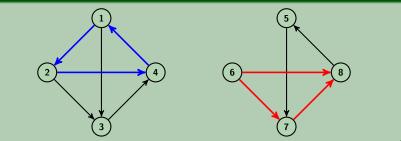
	а	b	с	d	е	f	g	h
In-Degree	1	2	2	1	0	1	1	0
Out-Degree	2	0	1	1	3	0	0	1

Re-examining Paths and Cycles on Directed Graphs

Paths?



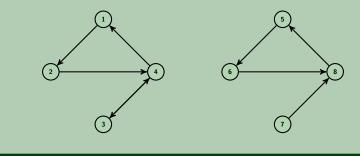
Cycle



Making A Connection!

Definition (Strongly Connected Directed Graph)

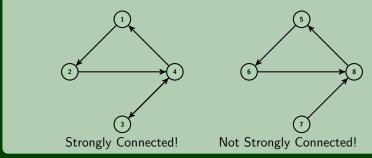
We say a directed graph is **strongly connected** iff for every pair of vertices, $u, v \in V$, there is a path from u to v.



Making A Connection!

Definition (Strongly Connected Directed Graph)

We say a directed graph is **strongly connected** iff for every pair of vertices, $u, v \in V$, there is a path from u to v.



Definition (Weakly Connected Directed Graph)

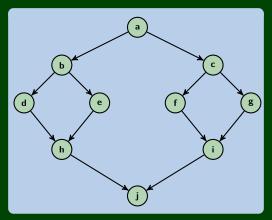
We say a directed graph is **weakly connected** iff the underlying undirected graph is connected.

That is, if we "undirected the edges", if the graph is connected, then the digraph is weakly connected.

Directed Acyclic Graphs: DAGs

Definition (DAG)

A DAG is a directed, acyclic graph.



By "acyclic", we mean in the directed sense.

DAGs vs. Trees?

Is there a tree that isn't a DAG?

Is there a DAG that isn't a tree?

DAGs vs. Trees?

All trees are DAGs (remember, trees must be acyclic and connected!).

Not all DAGs are trees. See previous slide. Also, DAGs don't have to be connected!

Why DAGs?

They come up a lot in practice. Cycles can be icky. Examples:

- Any sort of scheduling problem (scheduling your courses, scheduling fork-join threads, ...)
- Causal Structures (Baysian Networks)

Genealogy

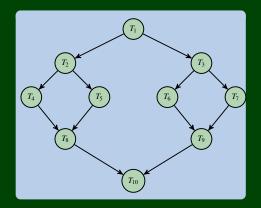
...

Topological Sort

Topological Sort

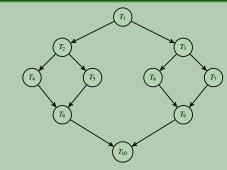
Given a DAG (G = (V, E)), output all the vertices in an order such that no vertex appears before any vertex that has an edge to it.

"Output an order to process the graph that meets all dependencies"



Topological Sort

How Many Valid Topological Sorts?



- $\blacksquare T_1, T_2, T_3, T_4, T_5, T_6, T_7, T_8, T_9, T_{10}$
- $\bullet T_1, T_2, T_4, T_3, T_5, T_6, T_7, T_8, T_9, T_{10}$
- $\bullet T_1, T_2, T_5, T_4, T_3, T_6, T_7, T_8, T_9, T_{10}$
- $\blacksquare T_1, T_3, T_6, T_7, T_9, T_2, T_5, T_4, T_8, T_{10}$

10

An Idea

Implementing Topological Sort

Throw all the in-degrees in a priority queue. removeMin() repeatedly.

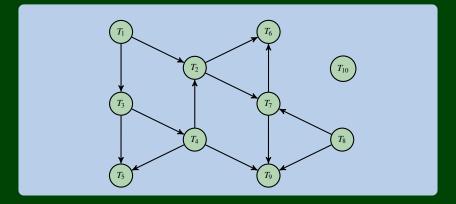
- This works, but it's too slow.
- Insight: PriorityQueues must deal with negative numbers; indegree will never be negative!
- Instead: Split ready vs. not ready (0 vs. non-zero) sets
- The "ready set" is a worklist!

	Setup
1	<pre>output = []</pre>
2	deps = {}
	worklist = []
4	<pre>for (v : vertices) {</pre>
5	<pre>deps[v] = in-degree(v);</pre>
6	<pre>if (deps[v] == 0) {</pre>
7	worklist.add(v);
8	}
9	}

Do Work

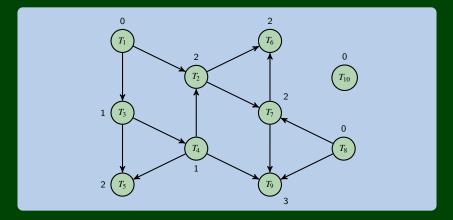
1	<pre>while (worklist.hasWork()) {</pre>
2	<pre>v = worklist.next();</pre>
3	<pre>output.add(v);</pre>
4	<pre>for (w : neighbors(v)) {</pre>
5	deps[w] -= 1
6	if (deps[w] == 0) {
7	<pre>worklist.add(w);</pre>
8	}
9	}
0	}

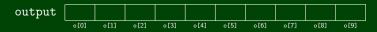
worklist \leftarrow



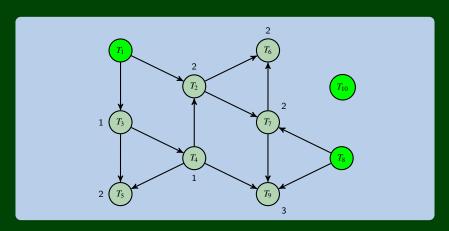


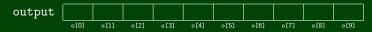
worklist \leftarrow



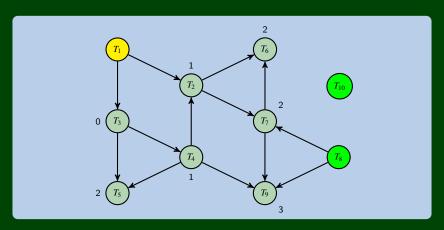


worklist $\leftarrow T_1 \mid T_8 \mid T_{10} \leftarrow$



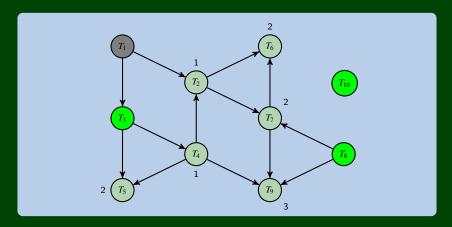


worklist $\leftarrow T_8 \mid T_{10} \leftarrow$



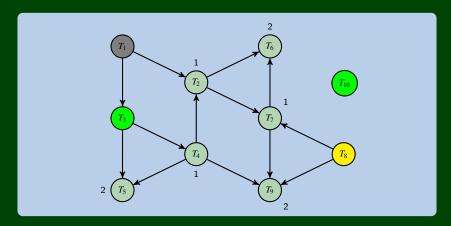


worklist
$$\leftarrow T_8 \mid T_{10} \mid T_3 \leftarrow$$



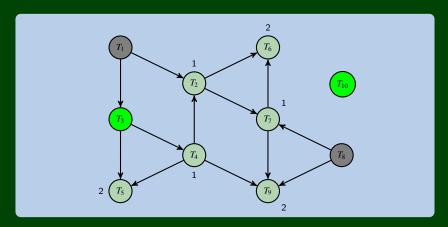


worklist
$$\leftarrow T_{10} \quad T_3 \leftarrow$$



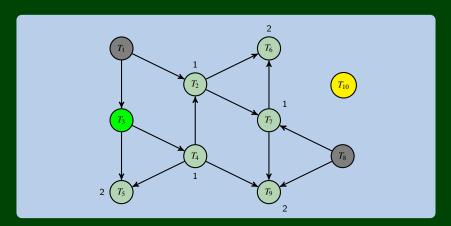


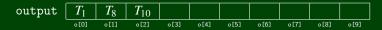
worklist
$$\leftarrow T_{10} \quad T_3 \leftarrow$$



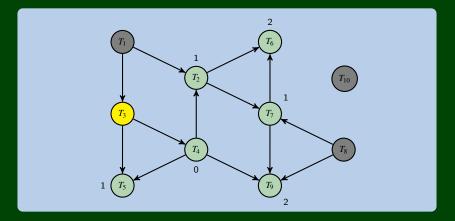


worklist $\leftarrow T_3 \leftarrow$



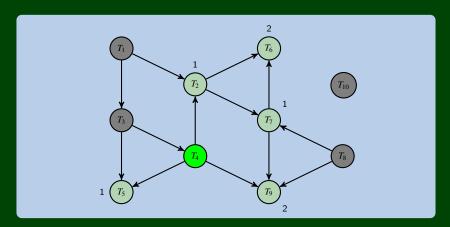


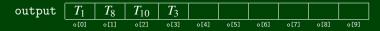
worklist \leftarrow



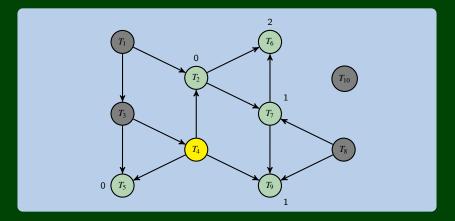


worklist $\leftarrow T_4 \leftarrow$



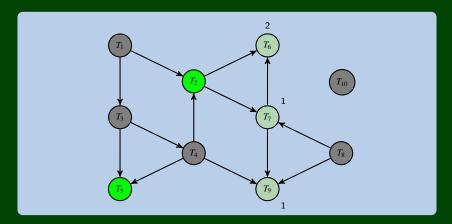


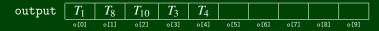
worklist \leftarrow



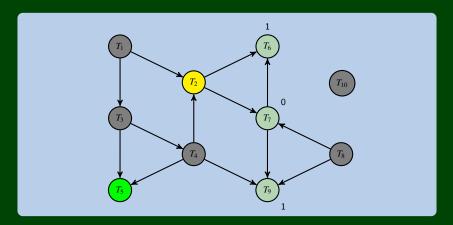


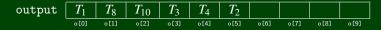
worklist
$$\leftarrow T_2 \quad T_5 \leftarrow$$



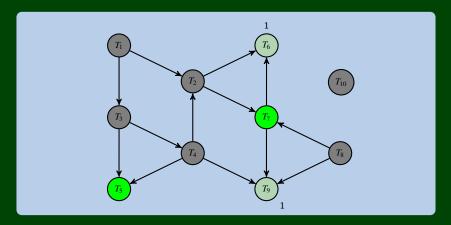


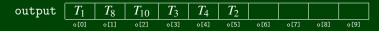
worklist $\leftarrow T_5 \leftarrow$



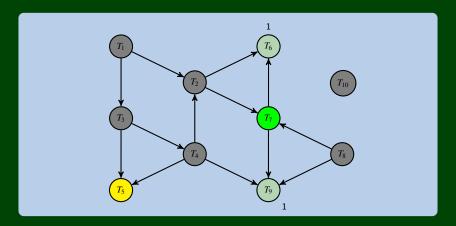


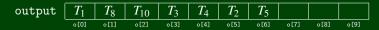
worklist
$$\leftarrow T_5 \quad T_7 \leftarrow$$



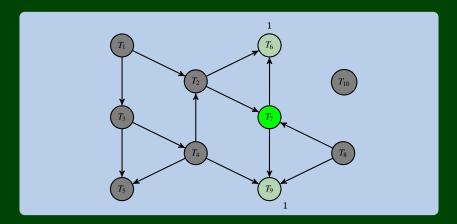


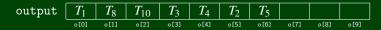
worklist $\leftarrow T_7 \leftarrow$



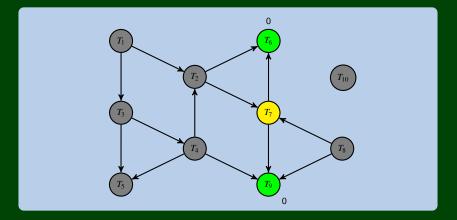


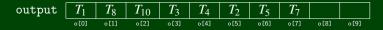
worklist $\leftarrow T_7 \leftarrow$



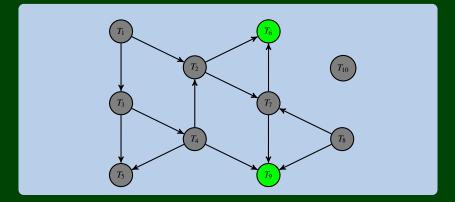


worklist \leftarrow

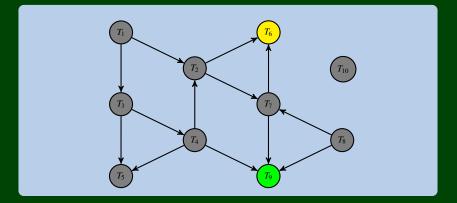




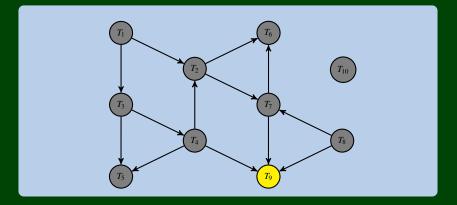
worklist
$$\leftarrow T_6 \quad T_9 \leftarrow$$

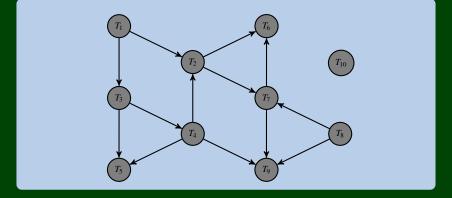


worklist $\leftarrow \boxed{T_9} \leftarrow$



worklist \leftarrow





What happens if there is a cycle?

Our worklist will be empty before we've processed all of the vertices. (e.g., "there are no nodes ready to print next, but we haven't gone through all of them)

In this case: our algorithm should throw a "not a DAG exception".

Runtime?

- Setup: We follow every edge for every vertex: $\mathcal{O}(|V| + |E|)$
- We add/remove each vertex from the work list once: $\mathcal{O}(|V|)$
- We decrement each indegree until zero (once for each edge): $\mathcal{O}(|E|)$
- So, overall, it's graph linear!